

für Angewandte Wissenschafte

ICAS Workshop, September 11-12, 2017 Intelligent and Autonomous Technologies in Aeronautics - Software Engineering and Unmanned Aerial Systems

Integrating drones into civil air traffic - challenges and concepts

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- Drones and applications
- Airspace and users
- Concepts for airspace integration of civilian drones
- Conclusions

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Unmanned Aircraft



ZHAW UMARS





Amazon Prime Air

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Northrop Grumman RQ-180

Prox Dynamics PD-100 PRS 'Black Hornet '

Toys develop into professional tools







GoPro KARMA



Parrot DISCO FPV



DJI Mavic Pro

- Size: 85 mm x 85 mm x 200 mm folded
- Span (engine to engine): 335 mm
- Weight: 750 gram
- Maximum radio distance: 7 km
- Maximum endurance: 27 minutes
- Maximum airspeed: 64 km/h
- Camera: 4000 x 3000 pixels
- price: \$1000



Swiss Federal Rail Service SBB using drones to predict debris avalanches

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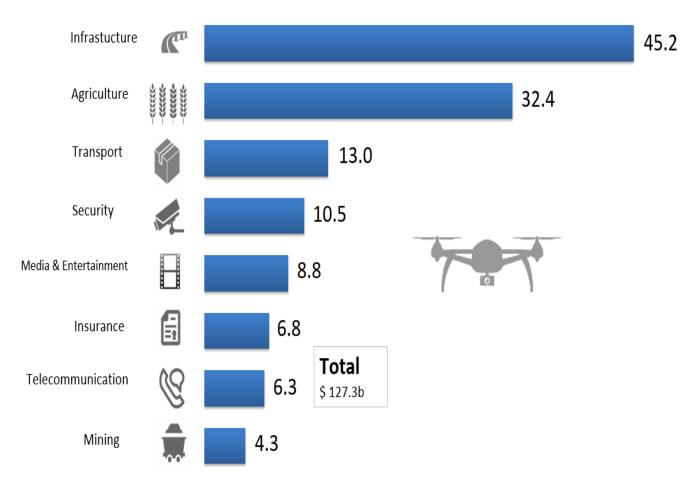


Source: Drohnen helfen der SBB, NZZ 24. August 2017 / SRF Video



The Industries Where Drones Could Really Take off

Value of drone powered solutions to industries in 2015 (billion U.S. dollars)



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Airspace structure of the FIR Switzerland

Luftraumklassierung und -struktur

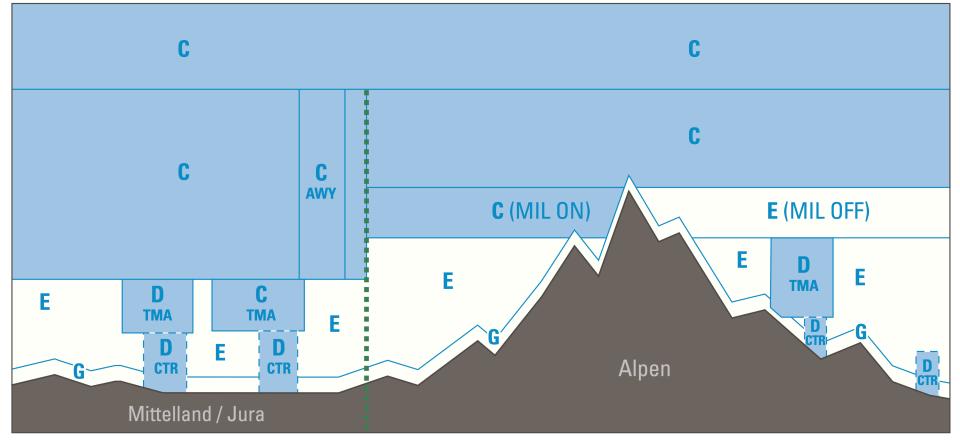
Classification et structure de l'espace aérien

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Source: Skyguide <u>VFR-Guide</u> page 112

Airspace users

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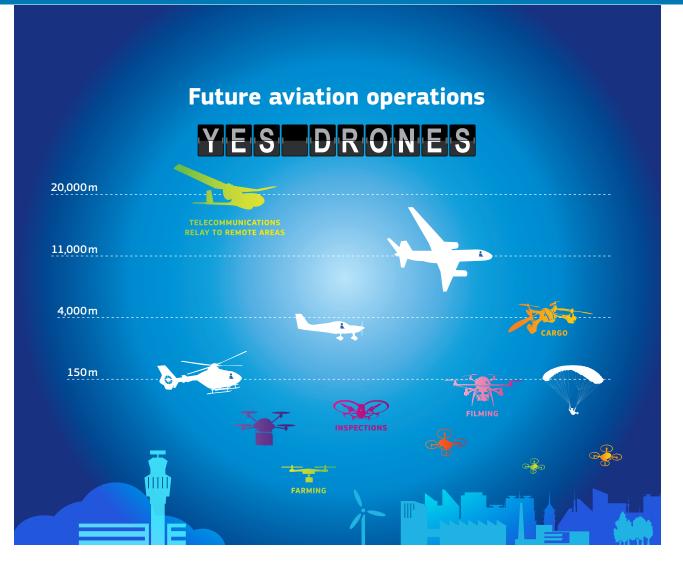




Airspace users

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Source: European Commission

11

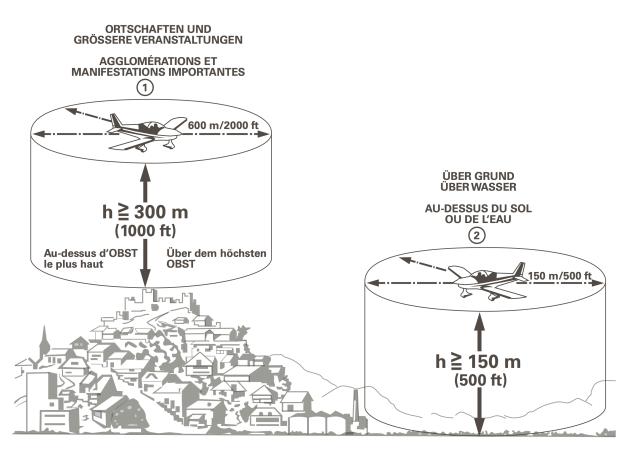
Visual Flight Rules (VFR): Minimum altitude

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Mindestflughöhen über Grund Hauteurs minimales de vol



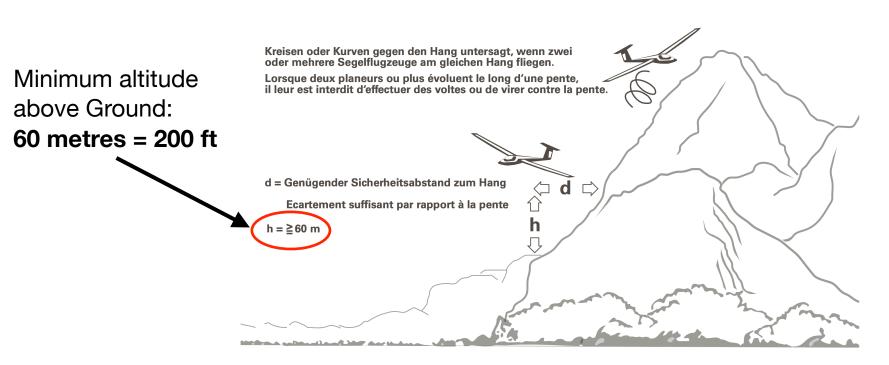
gilt als Motorflugzeug est considéré comme avion



Visual Flight Rules (VFR): Ridge soaring rules

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Hangflugregeln Règles pour le vol de pente

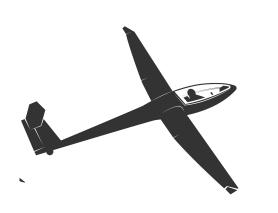


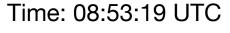
Source: Skyguide <u>VFR-Guide</u> page 97

Gliders below 500 ft AGL



Alzate Brianza





Distance Triangle

Barcelbnnette Gld

MSL: 2215 m Vario: +1.4 m/ Speed: 147 km/h AGL: 33

08:00 09:00 10:00 11:00 12:00 13:00 14:00 15:00 15:00 17:00

limoisson Glb

<u>3500 m</u> 3**0**00 m

Geneve

Altitude above Ground Level (AGL): **33 m** = **108 ft**

Airspeed: 147 km/h

Source: OLC Gliding

548m

10 m

m Time: 08:53:19

Niese

Hahnenmoos

MSL: 2284 m Vario: -0.5 m/ Speed: 39 km/h AGL: 12

8:00 09:00 10:00 11:00 12:00 13:00 14:00 15:00 16:00

Paragliders below 500 ft AGL





Time: 08:16:21 UTC

OLC-PHG

Gruyeres

Rochers de Nave

Altitude above Ground Level (AGL): **12 m** = **40 ft**

Airspeed: 39 km/h

Source: OLC ParaHangGliding

4461 m

387 m

m Time: 08:16:21

Gliders and Paragliders below 500 ft AGL





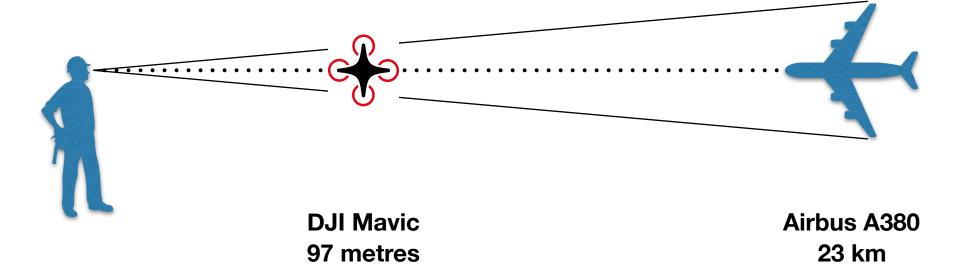


How do these guys avoid a collision?

The answer is: See & Avoid

Visual Flight Rules (VFR): See & Avoid

Usable visual acuity: 3 arc minutes = **0.05**°



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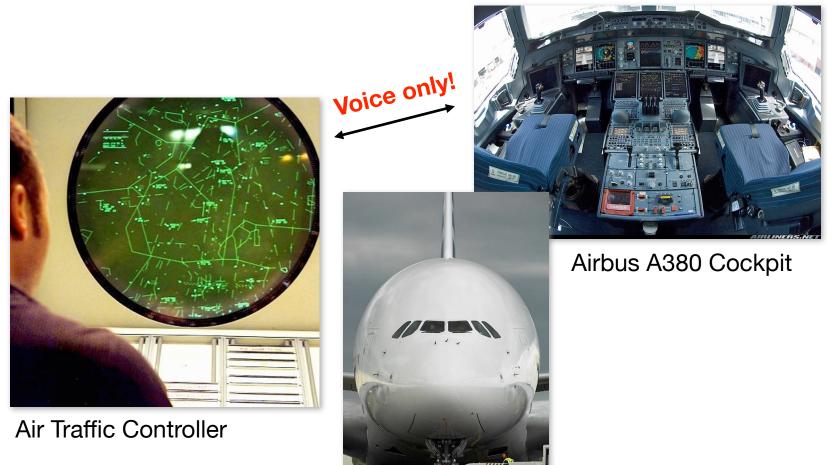
Calculated maximum viewing distance

Instrument Flight Rules (IFR): Separation by Air Traffic Control

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Communication and coordination with Air Traffic Control (ATC) in all phases of the flight.



Content

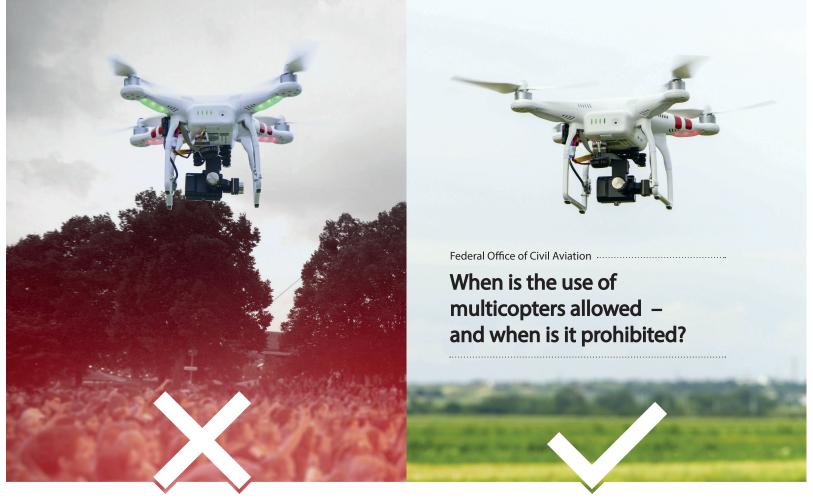


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Swiss FOCA: Rules for drone operations







Bundesamt für Zivilluftfahrt www.bazl.admin.ch

Schweizerische Eidgenossenschaft Confedération suisse Confederazione Svizzera Confederaziun svizra Swiss Confederation Bundesamt für Zivilluftfahrt BAZL Office fédéral de l'aviation civile OFAC Ufficio federale dell'aviazione civile UFAC Federal Office of Civil Aviation FOCA

Swiss FOCA: Rules for drone operations





Operation without the need for a permit



Remote controlled multicopters with a total weight of less than 30 kilograms and in permanent direct eye contact of the "Pilot"



Multicopters on model airfields and operated by participants in air shows



Multicopters on open ground and in populated areas without gatherings of people (groups of more than two dozen people). Always observe the principle of protection of privacy and never operate a drone in a nature conservation area.

-> (See RPAS Map)

.....

RPAS Map: www.bazl.admin.ch/karte-rpas Further information: www.bazl.admin.ch/rpas

Operation requiring a permit



Multicopters controlled with video goggles and without a second "pilot" in permanent direct eye contact

>30kg





Multicopters within a radius of less than 100 metres around gatherings of people outdoors, except at public air shows and on designated airfields for flying model aircraft



Multicopters operated within a radius of less than 5 kilometres around airfields / airports, and at an altitude higher than 150 metres above ground level in air traffic control zones; here the necessary permit has to be obtained from the airfield manager or air traffic control -> (See RPAS Map)



Please observe any other applicable cantonal or municipal restrictions and temporarily restricted airspace (e.g. above Davos during the World Economic Forum).

Contact E-mail: rpas@bazl.admin.ch

Remotely-Piloted Aircraft Systems (RPAS)

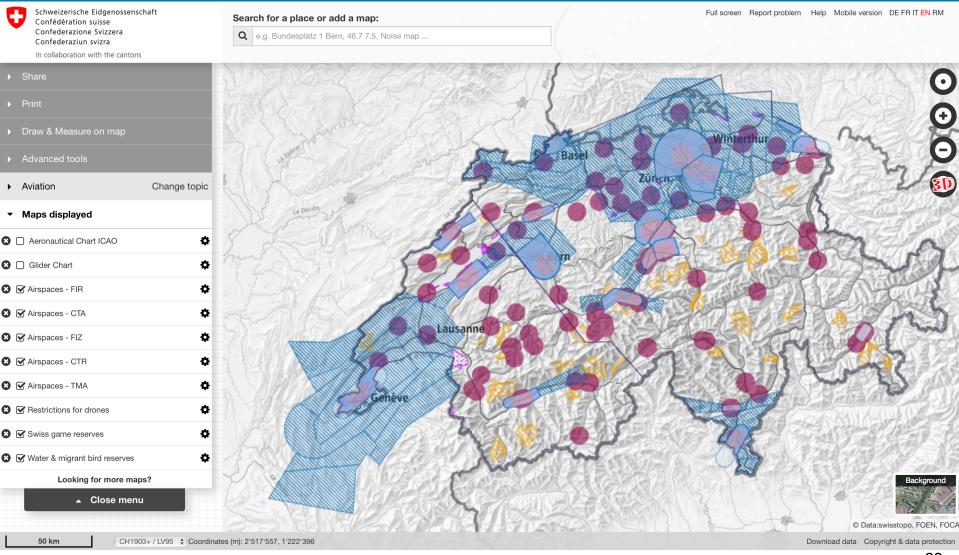




Swiss FOCA: RPAS Map

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Swiss Confederation: Map of RPAS no-flight zones

Drone operation in Visual Line of Sight (VLOS)

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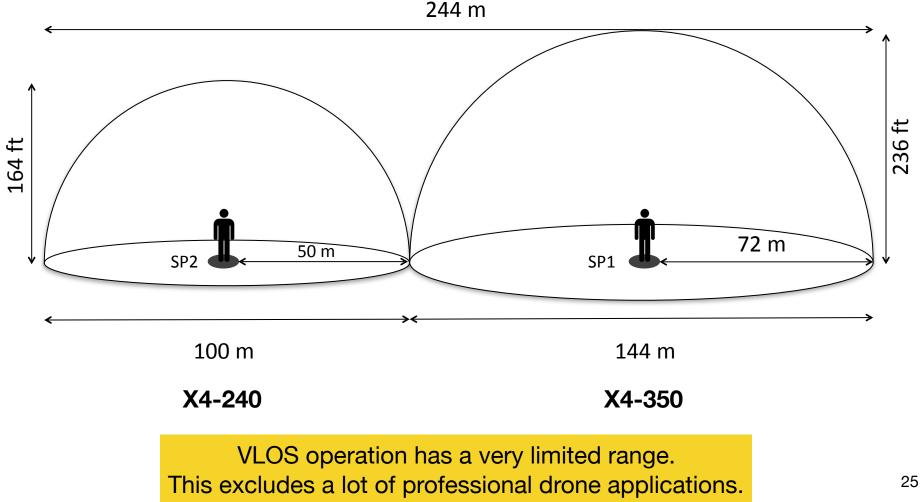


The flying testbeds of the ZHAW Centre for Aviation

Drone operation in Visual Line of Sight (VLOS)



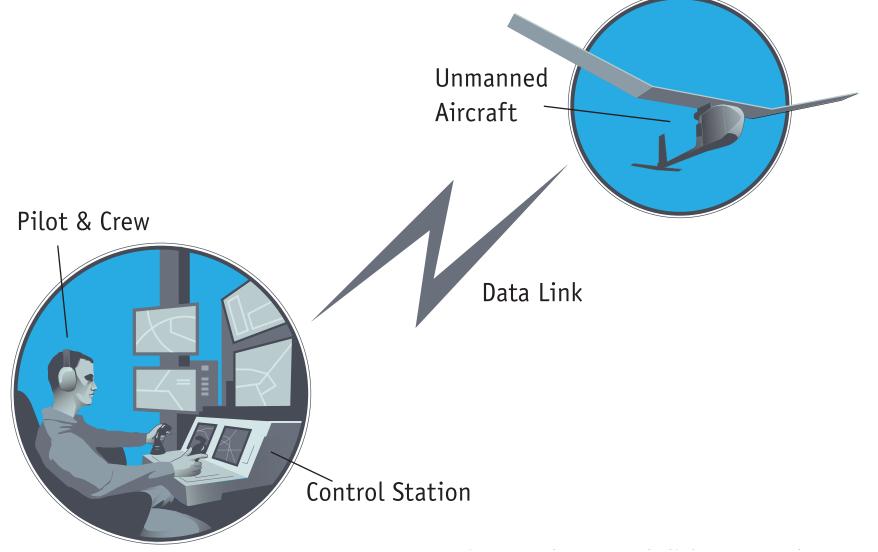
Flight test results for maximum VLOS range:



Drone operation Beyond Visual Line of Sight (BVLOS)

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BVLOS operation in controlled airspace: The challenge of voice communication



- Scenario 1: Voice between Remote Pilot (RP) and ATC Controller. Data link between RP and drone. feasible
- Scenario 2: ATM shifts from voice communication to data link communication.
 only a long term scenario
- Scenario 3: Drones with speech recognition.
 speech recognition still has high error probability
- Scenario 4: A separate Unmanned Air Traffic Management (UTM) for drones.
 ATC needs systems and procedures to merge UTM with classic ATM.

Detect & Avoid in controlled airspace: Airborne Collision Avoidance System (ACAS) Zürcher Hochschule für Angewandte Wissenschaften



Traffic Collision Avoidance System (TCAS)



TCAS II

TCAS Display [Allied Signal]

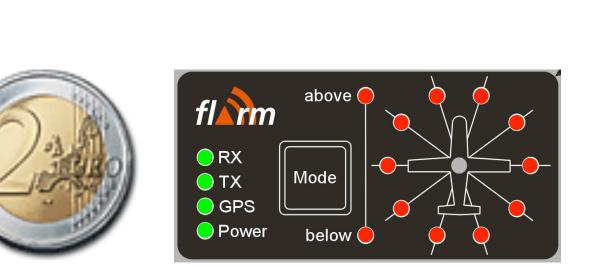
- If traffic separation by ATC fails, TCAS is the last resort to avoid collision.
- TCAS commands only vertical evasion manoeuvres.
- TCAS equipment does not fit into small drones.



Detect & Avoid in uncontrolled airspace: Flight Alarm (FLARM)

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- RX (Receive): illuminates if traffic is within range, requires GPS reception
- TX (Send): illuminates when transmitting own position, requires GPS reception
- GPS: illuminates during GPS reception, blinks 1-3 minutes when device is started
- Power: illuminates, if voltage is sufficient; blinks if voltage is low, shuts off below 8.5V
- FLARM is a Collision Warning System (CWS) not a Collision Avoidance System.
- FLARM is not certified.
- FLARM is not mandatory for VFR flight.

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Conclusions



- VLOS operation has a very limited range which excludes a lot of professional drone applications.
- There is VFR traffic below 500 ft AGL! Expect it to be fast (gliders) and vulnerable (paragliders), if you fly your drone there.
- Pilots do not (want to) "see & avoid" drones, drones have to "detect & avoid" other air traffic.
- BVLOS operation in uncontrolled airspace needs a certified (!) Detect & Avoid system which equals or excels "See & Avoid" of VFR aircraft.
- BVLOS in controlled airspace needs voice communication or an UTM managed by ATC.

Outlook

COMPUTERIZED AVIATION

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